## Solving a Log-Linearized RBC Model Algebraically

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These notes describe how to construct a log-linear approximation of an RBC model around a non-stochastic steady state and how to solve the linearized model algebraically using the method of undetermined coefficients. The procedure described below is used to produce the simulations on this webpage: [https://www.briancjenkins.com/simulations/centralized-rbc.html.](https://www.briancjenkins.com/simulations/centralized-rbc.html) The exercise is tedious and demonstrates the great value provided by the many computational tools and methods available for approximating and solving DSGE models.

The Model The equilibrium conditions of the model are given by:

$$
\varphi \left(1 - L_t\right)^{-\eta} = C_t^{-\sigma} W_t \tag{1}
$$

$$
C_t^{-\sigma} = \beta E_t \left[ C_{t+1}^{-\sigma} R_{t+1} + 1 - \delta \right] \tag{2}
$$

<span id="page-0-3"></span><span id="page-0-2"></span><span id="page-0-1"></span><span id="page-0-0"></span>
$$
W_t = (1 - \alpha) A_t K_t^{\alpha} L_t^{-\alpha}
$$
\n<sup>(3)</sup>

$$
R_t = \alpha A_t K_t^{\alpha - 1} L_t^{1 - \alpha} \tag{4}
$$

$$
K_{t+1} = I_t + (1 - \delta)K_t
$$
\n(5)

$$
Y_t = C_t + I_t \tag{6}
$$

<span id="page-0-7"></span><span id="page-0-6"></span><span id="page-0-5"></span><span id="page-0-4"></span>
$$
Y_t = A_t K_t^{\alpha} L_t^{1-\alpha} \tag{7}
$$

$$
\log A_{t+1} = \rho_a \log A_t + \epsilon_{t+1} \tag{8}
$$

Equation [\(1\)](#page-0-0) is the representative household's first-order condition for the optional choice of labor. Equation [\(2\)](#page-0-1) is the household's Euler equation reflecting an optimal choice of capital for period  $t + 1$ . Equations [\(3\)](#page-0-2) and [\(4\)](#page-0-3) are the firm sector's first-order conditions for optimal choices of labor and capital. Equations  $(5)$ ,  $(6)$ , and  $(7)$  describe the evolution of the aggregate capital stock, the goods market clearing condition, and the production function. Finally, equation [\(8\)](#page-0-7) indicates that log TFP follows an AR(1) process where  $\epsilon_{t+1} \sim \mathcal{N}(0, \sigma_{\epsilon}^2)$  is an exogenous shock process.

Steady State Let capital letters without time subscripts denote non-stochastic steady state values of the model variables. The steady state is given by the following system:

$$
\varphi \left( 1 - L \right)^{-\eta} = C^{-\sigma} W \tag{9}
$$

$$
C^{-\sigma} = \beta E \left[ C^{-\sigma} (R + 1 - \delta) \right] \tag{10}
$$

<span id="page-0-9"></span><span id="page-0-8"></span>
$$
W = (1 - \alpha)AK^{\alpha}L^{-\alpha}
$$
\n<sup>(11)</sup>

$$
R = \alpha A K^{\alpha - 1} L^{1 - \alpha} \tag{12}
$$

$$
K = I + (1 - \delta)K\tag{13}
$$

<span id="page-0-10"></span>
$$
Y = C + I \tag{14}
$$

$$
Y = AK^{\alpha}L^{1-\alpha} \tag{15}
$$

$$
\log A = \rho_a \log A \tag{16}
$$

In general, the nonlinear terms in equation [\(9\)](#page-0-8) prevent this system from being solved algebraically. However, most of the work can be done with algebra. First, note that steady state TFP is trivial:

<span id="page-0-12"></span><span id="page-0-11"></span>
$$
A = 1 \tag{17}
$$

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Next, use the Euler and capital demand equations to solve for the steady state capital-to-labor ratio:

<span id="page-1-0"></span>
$$
\frac{K}{L} = \left(\frac{\alpha A}{\beta^{-1} + \delta - 1}\right)^{\frac{1}{1-\alpha}}
$$
\n(18)

Next, use equations  $(9)$ ,  $(11)$ ,  $(13)$ ,  $(14)$ ,  $(15)$ , and  $(18)$  to obtain an equation that characterizes steady state labor:

$$
\varphi(1-L)^{-\eta}L^{\sigma} = (1-\alpha)\left[A(K/L)^{\alpha} - \delta(K/L)\right]^{-\sigma}A(K/L)^{\alpha}
$$
\n(19)

Note that the right side of equation [\(19\)](#page-1-1) is a constant. Solve [\(19\)](#page-1-1) numerically.

The remaining steady state values are readily obtained:

$$
K = (K/L)L \tag{20}
$$

<span id="page-1-1"></span>
$$
Y = AK^{\alpha}L^{1-\alpha} \tag{21}
$$

$$
W = (1 - \alpha)Y/L \tag{22}
$$

$$
R = \alpha Y/K \tag{23}
$$

 $I = \delta K$ (24)  $(25)$ 

$$
C = Y - I \tag{25}
$$

Log-linear Approximation Let lowercase letters represent the log deviations of variables from their steady states, e.g.:  $y_t = \log(Y_t) - \log(Y)$ . The log-linearized equilibrium conditions are:

<span id="page-1-2"></span>
$$
0 = -\sigma c_t + w_t - \frac{\eta L}{1 - L} l_t \tag{26}
$$

$$
-\sigma E_t c_{t+1} + \beta R E_t r_{t+1} = -\sigma c_t \tag{27}
$$

$$
0 = y_t - l_t - w_t \tag{28}
$$

<span id="page-1-6"></span><span id="page-1-3"></span>
$$
0 = y_t - k_t - r_t \tag{29}
$$

$$
k_{t+1} = \delta i_t + (1 - \delta)k_t \tag{30}
$$

<span id="page-1-5"></span><span id="page-1-4"></span>
$$
0 = \frac{C}{Y}c_t + \frac{I}{Y}i_t - y_t
$$
\n
$$
(31)
$$

$$
0 = a_t + \alpha k_t + (1 - \alpha)l_t - y_t \tag{32}
$$

$$
a_{t+1} = \rho a_t + \epsilon_{t+1} \tag{33}
$$

Note that all forward-looking variables have been moved to the left sides of the equations and contemporaneous variables to the left.

Solution The goal is to use algebra to eliminate all endogenous variables from the system except for  $k_t$  and to solve the resulting second-order difference equation using the method of undetermined coefficients. To begin, take  $(26)$  and use equations  $(28)$ ,  $(31)$ , and  $(32)$  to express labor as a function of only  $a_t$ ,  $k_t$ , and  $c_t$ :

$$
l_t = \phi_1 a_t + \phi_2 k_t + \phi_3 c_t \tag{34}
$$

where:

$$
\phi_1 = \frac{1 - L}{\alpha + (\eta - \alpha)L} \tag{35}
$$

$$
\phi_2 = \alpha \phi_1 \tag{36}
$$

$$
\phi_3 = -\sigma \phi_1 \tag{37}
$$

Then, use the capital evolution equation  $(30)$  and the market clearing condition  $(31)$  to express consumption as a function of  $a_t$ ,  $k_t$ , and  $k_{t+1}$ :

$$
c_t = \phi_4 a_t + \phi_5 k_t + \phi_6 k_{t+1} \tag{38}
$$

where:

$$
\phi_4 = \frac{1 + (1 - \alpha)\phi_1}{C/Y - (1 - \alpha)\phi_3} \tag{39}
$$

$$
\phi_5 = \frac{\alpha + (1 - \alpha)\phi_2 + \delta^{-1}(1 - \delta)I/Y}{C/Y - (1 - \alpha)\phi_3} \tag{40}
$$

$$
\phi_6 = -\frac{\delta^{-1}I/Y}{C/Y - (1 - \alpha)\phi_3} \tag{41}
$$

Next, use the previous two results to write the real rental rate as a function of only  $a_t$ ,  $k_t$ , and  $k_{t+1}$ :

$$
r_t = \phi_7 a_t + \phi_8 k_t + \phi_9 k_{t+1} \tag{42}
$$

where:

$$
\phi_7 = 1 + (1 - \alpha)\phi_1 + (1 - \alpha)\phi_3\phi_4 \tag{43}
$$

$$
\phi_8 = \alpha - 1 + (1 - \alpha)\phi_2 + (1 - \alpha)\phi_3\phi_5 \tag{44}
$$

$$
\phi_9 = (1 - \alpha)\phi_3\phi_6\tag{45}
$$

Now, note that  $E_t a_{t+1} = \rho a_t$  $E_t a_{t+1} = \rho a_t$  $E_t a_{t+1} = \rho a_t$  and express the Euler equation in terms of only  $a_t$ ,  $k_t$ ,  $k_{t+1}$ , and  $E_t k_{t+2}$ <sup>1</sup>

$$
0 = \phi_{10}a_t + \phi_{11}k_t + \phi_{12}k_{t+1} + \phi_{13}E_tk_{t+2}
$$
\n
$$
(46)
$$

where:

<span id="page-2-1"></span>
$$
\phi_{10} = \sigma \phi_4 (1 - \rho) + \beta R \phi_7 \rho \tag{47}
$$

$$
\phi_{11} = \sigma \phi_5 \tag{48}
$$

$$
\phi_{12} = \sigma(\phi_6 - \phi_5) + \beta R \phi_8 \tag{49}
$$

$$
\phi_{13} = \beta R \phi_9 - \sigma \phi_6 \tag{50}
$$

Equation [\(46\)](#page-2-1) is a second-order difference equation in  $k_t$ .

I solve the difference equation in [\(46\)](#page-2-1) using the method of undetermined coefficients. Guess that the solution takes the following form:

<span id="page-2-3"></span><span id="page-2-2"></span>
$$
k_{t+1} = \pi_1 a_t + \pi_2 k_t \tag{51}
$$

where the coefficients  $\pi_1$  and  $\pi_2$  are to be found. The guess implies that the expectation  $k_{t+2}$  is:

$$
E_t k_{t+2} = \pi_1 \rho a_t + \pi_2 k_{t+1} \tag{52}
$$

Plug [\(51\)](#page-2-2) and [\(52\)](#page-2-3) into [\(46\)](#page-2-1).  $\pi_1$  and  $\pi_2$  are determined by the following system:

$$
\phi_{13}\pi_2^2 + \phi_{12}\pi_2 + \phi_{11} = 0 \tag{53}
$$

$$
\phi_{10} + \phi_{12}\pi_1 + \phi_{13}\pi_1(\rho + \pi_2) = 0 \tag{54}
$$

Find  $\pi_2$  by taking the smallest root of the following quadratic equation:

$$
\phi_{10} + \phi_{12}\pi_1 + \phi_{13}\pi_1(\rho + \pi_2) = 0
$$
\n(55)

Find  $\pi_1$  to be:

$$
\boxed{\pi_1 = -\frac{\phi_{10}}{\phi_{12} + \phi_{13}(\rho + \pi_2)}}\tag{56}
$$

Solutions for  $c_t$ ,  $r_t$ , and  $l_t$ :

$$
c_t = (\phi_4 + \phi_6 \pi_1) a_t + (\phi_5 + \phi_6 \pi_2) k_t
$$
\n(57)

$$
r_t = (\phi_7 + \phi_9 \pi_1) a_t + (\phi_8 + \phi_9 \pi_2) k_t
$$
\n(58)

$$
l_t = [\phi_1 + \phi_3(\pi_4 + \phi_6 \pi_1)] a_t + [\phi_2 + \phi_3(\pi_5 + \phi_6 \pi_2)] k_t
$$
\n(59)

<span id="page-2-0"></span><sup>&</sup>lt;sup>1</sup>Note that  $a_{t+1}$  is determined outside of this equation.

Finally, the solutions for the variables  $i_t,\,y_t,$  and  $w_t$  are found to be:

$$
y_t = [1 + \phi_1 + \phi_3(\pi_4 + \phi_6 \pi_1)] a_t + [\alpha + \phi_2 + \phi_3(\pi_5 + \phi_6 \pi_2)] k_t
$$
(60)  

$$
i_t = \delta^{-1} \pi_1 a_t + \delta^{-1} (\pi_2 + \delta - 1) k_t
$$
(61)

$$
w_t = \left[1 - \alpha(\phi_1 + \phi_3 \pi_4 + \phi_3 \phi_6 \pi_1)\right] a_t + \alpha \left[1 - (\phi_2 + \phi_3 \pi_5 + \phi_3 \phi_6 \pi_2)\right] k_t \tag{62}
$$